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Knowledge and action:  
how should we combine their logics?

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(work with E. Lorini, F. Maffre, F. Schwarzentruher)

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# Outline

- ① Motivation: simple logics of action and knowledge needed
- ② Adding higher-order observability information
- ③ Application: the gossip problem
- ④ Adding public announcements
- ⑤ Application: the muddy children puzzle
- ⑥ Application: boolean games

# Logics of knowledge and action

- fruitful in CS since 30+ years
  - epistemic temporal logics  
[Halpern et col., Lomuscio, . . . ,  $\geq 1990$ ]
  - epistemic extension of the situation calculus  
[Scherl & Levesque, . . . ,  $\geq 1995$ ]
  - Dynamic Epistemic Logics DEL  
[van Benthem, Moss, Baltag, van Ditmarsch, . . . ,  $\geq 2000$ ]
- typically multi-dimensional modal logics
  - high complexity; often undecidable
- simplest combined logic of knowledge and action?
  - a typical question of philosophical logic
  - also relevant for computer science

# Logics of knowledge and action

- idea [v.d.Hoek & Wooldridge, inspired from model checkers]:
  - ground action on propositional control
  - ground knowledge on propositional observability

- logics:

ECL-PO = “Epistemic Coalition Logic of Propositional Control with Partial Observability” [vdHTW11]

LRC = “Logic of Revelation and Concealment” [vdHIW12]

- this talk:
  - reduce to *Dynamic Logic of Propositional Assignments* DL-PA
  - overcome some limitations of the original approach

# Grounding action on propositional control

agent  $i$  controls propositional variable  $p$  or not

- define accessibility relation for group of agents  $J \subseteq \text{Agt}$ :

$$R_J = \{(v, v') : v(p) = v'(p) \text{ if } p \in PVar \text{ not controlled by any } i \in J\}$$

- coalitional effectivity *ceteris paribus*:

$$vR_Jv' = \text{at } v, \text{ if the other agents don't act then } J \text{ can guarantee that the next state of the world is } v'$$

- interpret operator of coalitional effectivity:

$$v \models \diamond_J \varphi \text{ iff } v' \models \varphi \text{ for every } v' \text{ such that } vR_Jv'$$

$\implies$  Coalition Logic of Propositional Control

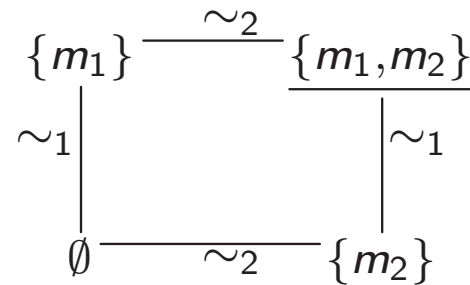
- approximates ATL/Pauly's operator of coalitional effectivity:

$$\langle\langle \{i\} \rangle\rangle X \varphi \approx \diamond_{\{i\}} \square_{\text{Agt} \setminus \{i\}} \varphi$$

# Grounding knowledge on propositional observability

agent  $i$  observes whether propositional variable  $p$  is true or not

- muddy children: child 1 sees whether child 2 is muddy; doesn't see whether 1 is muddy
- define indistinguishability relation:



$$\sim_i = \{(v, v') : v(p) = v'(p) \text{ for every } p \in PVar \text{ observed by } i\}$$

$\implies$  equivalence relation on the set of all valuations

- interpret epistemic operator as usual:

$$v \models K_i \varphi \text{ iff } v' \models \varphi \text{ for every } v' \text{ such that } v \sim_i v'$$

- pushes the envelope of the 'DEL philosophy' of replacing accessibility relations by model updates

(while DELs still have accessibility relations for knowledge)

# Propositional observability: properties

+ all axiom schemas of S5 valid

– observability is common knowledge:

$$(K_i p \vee K_i \neg p) \rightarrow K_j (K_i p \vee K_i \neg p)$$

$$\neg(K_i p \vee K_i \neg p) \rightarrow K_j \neg(K_i p \vee K_i \neg p)$$

– distributes over disjunction:

$$K_i (p \vee q) \leftrightarrow (K_i p \vee K_i q)$$

so:

- initial situation of the muddy children puzzle can be modelled
- ... but not the situation after the father's announcement "one of you is muddy"!

– related:

- logic only accounts for observation but not for *communication*



# Embedding into DL-PA

- can be captured in *Dynamic Logic of Propositional Assignments* DL-PA

1. introduce new propositional variables

$$C_i p = \text{“}i \text{ controls } p\text{”}$$

$$S_i p = \text{“}i \text{ sees } p\text{”}$$

2. identify  $\diamond_i$  and  $K_i$  with **assignment programs**:

for  $\varphi$  boolean with  $PVar(\varphi) = \{p_1, \dots, p_n\}$ ,

$$\begin{aligned} \diamond_i \varphi \leftrightarrow & \left\langle \left( \neg C_i p_1? \sqcup (C_i p_1?; (+p_1 \sqcup -p_1)) \right); \right. \\ & \dots; \\ & \left. \left( \neg C_i p_n? \sqcup (C_i p_n?; (+p_n \sqcup -p_n)) \right) \right\rangle \varphi \end{aligned}$$

$$\begin{aligned} K_i \varphi \leftrightarrow & \left[ \left( S_i p_1? \sqcup (\neg S_i p_1?; (+p_1 \sqcup -p_1)) \right); \right. \\ & \dots; \\ & \left. \left( S_i p_n? \sqcup (\neg S_i p_n?; (+p_n \sqcup -p_n)) \right) \right] \varphi \end{aligned}$$

$\implies$  start with innermost modal operators!

3. axiomatize exclusive and exhaustive control

$$\left( \bigwedge \neg(C_i p \wedge C_j p) \right) \wedge \left( \bigvee C_i p \right)$$

## DL-PA

- assignment programs built by the PDL program operators from

$+p =$  “make  $p$  true”

$-p =$  “make  $p$  false”

- generalizes QBF:

$$\forall p.\varphi \leftrightarrow [+p \sqcup -p]\varphi$$

- compact models
  - valuations of classical propositional logic
- PSPACE complete (both model checking and SAT)
- uniform substitution does not preserve validity

# Adding higher-order observability information

## Higher-order observability

- idea: introduce **higher-order visibility atoms**

$$S_i p \quad = \text{“}i \text{ sees the value of } p\text{”}$$

$$S_i S_j p \quad = \text{“}i \text{ sees whether } j \text{ sees the value of } p\text{”}$$

$$S_i S_j S_k p \quad = \text{“} \dots \text{”}$$

- general schema as before:

$$K_i \varphi \leftrightarrow [\pi_{i, \text{Atm}(\varphi)}] \varphi$$

$$\text{where } \pi_{i, \text{Atm}(\varphi)} = (S_i \alpha_1? \sqcup (\neg S_i \alpha_1?; (+\alpha_1 \sqcup -\alpha_1))); \dots$$

examples:

$$K_i p \leftrightarrow p \wedge S_i p$$

$$K_i \neg p \leftrightarrow \neg p \wedge S_i p$$

$$K_i K_j p \leftrightarrow K_i (p \wedge S_j p)$$

$$\leftrightarrow K_i p \wedge K_i S_j p$$

$$\leftrightarrow p \wedge S_i p \wedge S_j p \wedge S_i S_j p$$

DEL-PA0 = DEL of Propositional Assignment and Observation

# Language of DEL-PAO

- visibility atoms:

$$\alpha ::= p \mid S_i \alpha \mid JS \alpha$$

with  $p$  propositional variable and  $i$  agent

$$\begin{aligned} p &= \dots \\ S_i \alpha &= \dots \\ JS \alpha &= \text{“all agents } \textit{jointly} \textit{ see whether } \alpha\text{”} \end{aligned}$$

- formulas and programs as in PDL:

$$\begin{aligned} \varphi &::= \alpha \mid \neg \varphi \mid \varphi \wedge \varphi \mid K_i \varphi \mid CK \varphi \mid [\pi] \varphi \\ \pi &::= +\alpha \mid -\alpha \mid \pi; \pi \mid \pi \sqcup \pi \mid \varphi? \end{aligned}$$

with  $i$  agent and  $\alpha$  visibility atom

## DEL-PAO: valuations

- valuation = sets of visibility atoms  $v$
- define indistinguishability relations:
  - $v \sim_i v'$  iff  $\forall \alpha, \text{ if } S_i \alpha \in v \text{ then } v(\alpha) = v'(\alpha)$
  - $v \sim_{Agt} v'$  iff  $\forall \alpha, \text{ if } JS \alpha \in v \text{ then } v(\alpha) = v'(\alpha)$
- problem: are reflexive, but neither transitive nor symmetric
  - $\emptyset \sim_i v$  for every  $v$
  - $v \not\sim_i \emptyset$  as soon as  $p \in v$  and  $S_i p \in v$

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  - $\emptyset \sim_i v$  for every  $v$
  - $v \not\sim_i \emptyset$  as soon as  $p \in v$  and  $S_i p \in v$
- solution: valuations must be **introspective**

# DEL-PA0: introspective valuations

## Definition

$v$  is **introspective** iff

1.  $S_i S_i \alpha \in v$
2.  $JS JS \alpha \in v$
3.  $JS S_i S_i \alpha \in v$
4. if  $JS \alpha \in v$  then  $S_i \alpha \in v$
5. if  $JS \alpha \in v$  then  $JS S_i \alpha \in v$

## Theorem

*introspective valuations contain all atoms of form “ $\dots S_i S_i \dots p$ ” and “ $\dots JS JS \dots p$ ”*

## Theorem

*$\sim_i$  and  $\sim_{Agt}$  are equivalence relations on introspective valuations*



# DEL-PAO: interpretation of formulas

- interpretation of formulas:

$$v \models \alpha \quad \text{iff} \quad \alpha \in v$$

$$v \models K_i \varphi \quad \text{iff} \quad v' \models \varphi \text{ for every } v \sim_i v'$$

$$v \models CK \varphi \quad \text{iff} \quad v' \models \varphi \text{ for every } v \sim_{Agt} v'$$

$$v \models [\pi] \varphi \quad \text{iff} \quad v' \models \varphi \text{ for every } v R_\pi v'$$

- interpretation of programs:

$$v R_{+\alpha} v' \quad \text{iff} \quad v' = v \cup \{\alpha \text{ and its introspective consequences}\}$$

$$v R_{-\alpha} v' \quad \text{iff} \quad \alpha \text{ is not an introspectively valid atom} \\ \text{and } v' = v \setminus \{\alpha \text{ and its causes}\}$$

$$v R_{\pi_1; \pi_2} v' \quad \text{iff} \quad \text{there is } v'' \text{ such that } v R_{\pi_1} v'' R_{\pi_2} v'$$

$$v R_{\pi_1 \sqcup \pi_2} v' \quad \text{iff} \quad v R_{\pi_1} v' \text{ or } v R_{\pi_2} v'$$

$$v R_{\varphi?} v' \quad \text{iff} \quad v = v' \text{ and } v \models \varphi$$

# Valid in introspective valuations

- S5 axiom schemas valid for  $K_i$  :

$$K_i \varphi \rightarrow \varphi$$

$$K_i \varphi \rightarrow K_i K_i \varphi$$

$$\neg K_i \varphi \rightarrow K_i \neg K_i \varphi$$

- fixed-point axiom schema valid for CK :

$$CK \varphi \leftrightarrow \varphi \wedge \bigwedge_i K_i CK \varphi$$

- induction axiom schema **invalid** for CK :

$$\varphi \wedge CK (\varphi \rightarrow \bigwedge_i K_i CK \varphi) \not\vdash CK \varphi$$

## Properties of DEL-PA0, ctd.

- sound and complete axiomatization

1. reduction axioms for  $K_i$ ,  $CK$ ,  $[\pi]$

$$K_i \varphi \leftrightarrow [\pi_{i, ATM(\varphi)}] \varphi$$

$$CK \varphi \leftrightarrow [\pi_{Agt, ATM(\varphi)}] \varphi$$

$$[\pi \sqcup \pi'] \varphi \leftrightarrow \dots$$

...

$$[+\alpha] \varphi \leftrightarrow \dots$$

$$[-\alpha] \varphi \leftrightarrow \dots$$

2. introspection axioms:

$$S_i S_i \alpha$$

$$JS JS \alpha$$

$$JS S_i S_i \alpha$$

$$JS \alpha \rightarrow S_i \alpha$$

$$JS \alpha \rightarrow JS S_i \alpha$$

3. modus ponens

4. rules of equivalence for  $K_i$ ,  $CK$ ,  $[\pi]$

# Properties of DEL-PA0, ctd.

- complexity: SAT and MC both PSPACE-complete

1. MC can be polynomially reduced to SAT
2. SAT can be polynomially reduced to MC
3. lower bound for MC: polynomial encoding of QBF

$$v \models \forall p.\varphi \text{ iff } v \models [+p \sqcup -p]\varphi$$

4. upper bound for MC: polynomial encoding into Dynamic Logic of Propositional Assignments DL-PA [HLT11, BHT13]

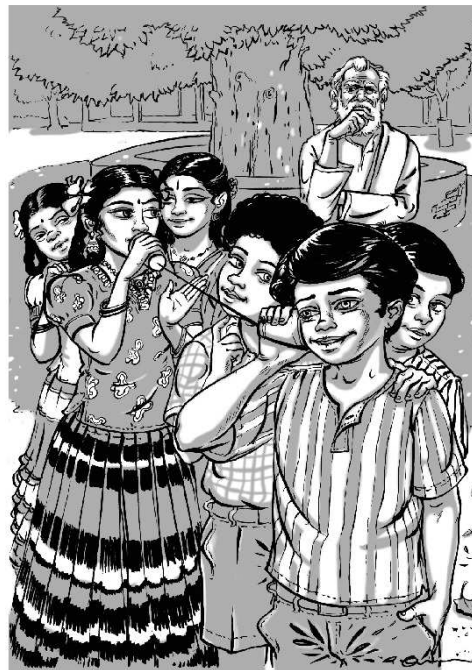
$\implies$  better than SAT for  $S5_n^{CK}$  (EXPTIME-complete)

# Application: the gossip problem

# The gossip problem

[Baker&Shostak, Discrete Mathematics 1972]

- six friends each with a secret  $\sigma_i$
- they can call each other to exchange every secret they know
- how many calls to spread all secrets among all friends?



(picture from [vDK15])

# The gossip problem

- goal: shared knowledge

$$\text{EK } \varphi = \bigwedge_{i \in \text{Agt}} K_i \varphi$$

(‘everybody knows’)

- optimal algorithm: 8 calls to obtain  $\text{EK}(\sigma_1 \wedge \dots \wedge \sigma_6)$ 
  - for  $n$  agents:  $2(n-1)$  calls
- versatile:
  - reasoning about social networks, disease spreading, ...
    - $\implies$  take some network structure into account
  - different kinds of protocols
    - $\implies$  distributed vs. centralized
- hot topic in the DEL community:
  - [AvDGvdH14, vDK15]
  - ongoing work by v.Ditmarsch, v.Eijck, v.d.Hoek, Grossi, Apt
- multiagent planning’s blocksworld?

# The gossip problem in DEL-PAO

call = program:

$$\begin{aligned}
 call_{ij} = & ((K_i \sigma_1?; +S_j \sigma_1) \sqcup \neg K_i \sigma_1?); \cdots ; ((K_i \sigma_6?; +S_j \sigma_6) \sqcup \neg K_i \sigma_6?); \\
 & ((K_j \sigma_1?; +S_i \sigma_1) \sqcup \neg K_j \sigma_1?); \cdots ; ((K_j \sigma_6?; +S_i \sigma_6) \sqcup \neg K_j \sigma_6?)
 \end{aligned}$$



# The gossip problem in DEL-PAO

call = program:

$$call_{ij} = ((K_i \sigma_1?; +S_j \sigma_1) \sqcup \neg K_i \sigma_1?); \dots; ((K_i \sigma_6?; +S_j \sigma_6) \sqcup \neg K_i \sigma_6?); \\ ((K_j \sigma_1?; +S_i \sigma_1) \sqcup \neg K_j \sigma_1?); \dots; ((K_j \sigma_6?; +S_i \sigma_6) \sqcup \neg K_j \sigma_6?)$$

For valuation  $v$  such that  $\sigma_i \in v$  and such that  $S_i \sigma_j \in v$  iff  $i=j$ :

$$v \models [call_{12}; call_{34}; call_{56}; call_{13}; call_{45}; call_{16}; call_{24}; call_{35}] \text{EK} \left( \bigwedge_{1 \leq j \leq 6} \sigma_j \right)$$

$$v \models \left\langle \left( \bigsqcup_{1 \leq i, j \leq 6} \neg S_i \sigma_j?; call_{ij} \right) \right\rangle^6 \text{EK} \left( \bigwedge_{1 \leq j \leq 6} \sigma_j \right)$$

$$v \models \left[ \left( \bigsqcup_{1 \leq i, j \leq 6} \neg S_i \sigma_j?; call_{ij} \right) \right]^5 \neg \text{EK} \left( \bigwedge_{1 \leq j \leq 6} \sigma_j \right)$$

# The gossip problem: attaining higher-order shared knowledge

- attain shared knowledge of level 2:

$$\text{EK EK} \left( \bigwedge_{1 \leq j \leq 6} \sigma_j \right)$$

- attain shared knowledge of level  $k$ :

$$\text{EK}^k \left( \bigwedge_{1 \leq j \leq 6} \sigma_j \right)$$

- algorithm with  $(k+1) \times (n-1)$  calls to attain shared knowledge of order 2 [Herzig & Maffre, submitted]
  - optimal?

# Adding public announcements

# Semantics: add current info state

[Herzig et al., ongoing]

- idea: evaluate epistemic formulas not only wrt agents' observations, but also wrt the current information state [CS15]
  - current information state = set of valuations  $W$
  - pointed model = information state  $W$  + valuation  $v$
- language: add public announcements
- truth conditions:
  - $W, v \models [\psi!] \varphi$  iff  $W, v \models \psi$  implies  $\|\psi\|_W, v \models \varphi$
  - $W, v \models K_i \varphi$  iff  $W, v' \models \varphi$  for every  $v' \in W$  s.th.  $v \sim_i v'$
- properties:
  - reduction axioms  $\implies$  decidable
  - PSPACE complete

# Application: the muddy children puzzle

## Application: the muddy children puzzle

for  $v$  such that  $S_i m_j \in v$  iff  $i \neq j$  and  $\text{JS } S_i m_j \in v$  for all  $i, j$ :

- ignorance persists for  $n-2$  rounds

$$v \models \text{Ignorance}$$

$$v \models [(\bigvee_i m_i) !] \text{Ignorance}$$

$$v \models [(\bigvee_i m_i) ? !] [\text{Ignorance} ? !] \text{Ignorance}$$

$$v \models [(\bigvee_i m_i) ? !] [\text{Ignorance} ? !]^{n-2} \text{Ignorance}$$

- shared and even common knowledge comes after  $n-1$  rounds

$$v \models [(\bigvee_i m_i) ? !] [\text{Ignorance} ? !]^{n-1} \text{EK } \bigwedge_i m_i$$

$$v \models [(\bigvee_i m_i) ? !] [\text{Ignorance} ? !]^{n-1} \text{CK } \bigwedge_i m_i$$

$$\text{with } \text{Ignorance} = \bigwedge_i (\neg K_i m_i \wedge \neg K_i \neg m_i)$$

# Application: boolean games

# Putting things together: accounting for epistemic boolean games

- boolean games
  - exclusive and exhaustive propositional control:

$$\left( \bigwedge_{i \neq j} \neg (C_i p \wedge C_j p) \right) \wedge \left( \bigvee_{i \in \text{Agt}} C_i p \right)$$

- strategy of agent  $i$  = truth values of  $i$ 's variables  
 $\implies$  strategy profile = valuation
- goal of agent  $i$  = propositional formula  $\gamma_i$   
 $\implies$  utility of strategy profile  $v$  is 1 if  $v \models \gamma_i$ ; is 0 otherwise
- strategy profile  $v$  is a Nash equilibrium iff

$$v \models \bigwedge_{i \in \text{Agt}} (\diamond_i \gamma_i \rightarrow \gamma_i)$$



# Putting things together: accounting for epistemic boolean games

- epistemic boolean games:
  - generalize propositional variables to atoms:  $S_i C_j p, \dots$
  - generalize goals to epistemic formulas
  - same definitions: strategy, Nash equilibrium, ...

example:

- agent 1 has a secret,  $s_1$ , and 2 has a secret,  $s_2$
- agent  $i$  may privately communicate his secret to  $j$ :  $+S_j s_i$
- both have goal of 'fair division of information':

$$\gamma_1 = \gamma_2 = K_1 s_2 \leftrightarrow K_2 s_1$$

example:

- ... and agent 3 shouldn't learn anything:

$$\gamma_1 = \gamma_2 = (K_1 s_2 \leftrightarrow K_2 s_1) \wedge \neg K_3 s_1 \wedge \neg K_3 \neg s_1 \wedge \neg K_3 s_2 \wedge \neg K_3 \neg s_2$$

# Conclusion and future work

- DEL-PAO = dynamic epistemic logic based on visibility
  - higher-order observations
    - no common knowledge of who sees what
- add public announcements
  - information state
- add propositional control: DEL-PAOC
- interesting complexity
- future work:
  - ?? from knowledge to belief
    - problem: guarantee introspection



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