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Architectural optimization of an epoxy-based hybrid sol–gel coating for the corrosion protection of a cast Elektron21 magnesium alloy

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**A B S T R A C T**

An epoxy-based hybrid sol–gel coating was prepared in various architectural configurations has been studied for the corrosion protection of a cast Elektron21 magnesium alloy. The creation of a single layer of this coating presents defects consisting of macro-pores and protuberances, which opens access for corrosive species to reach the metallic substrate. These defects are suspected to result from the high reactivity of the substrate, as well as to the irregular topography of the substrate disrupted by the microstructure of the own magnesium alloy. Hence, a sol–gel coating in bilayer architecture is proposed, where the first layer would “inert” the surface of the magnesium substrate, and the second layer would cover the defects of the first layer and also thickening the coating. The morphological characteristics of the sol–gel coatings were analyzed by scanning electron microscopy (SEM), and their corrosion behavior was evaluated by OCP (open circuit potential) monitoring and electrochemical impedance spectroscopy (EIS) in chloride media. It is shown that both the architectural arrangement and the individual thickness of the first and second layers have an important influence on the anticorrosion performances of the protective system, just as much as its global thickness.

1. Introduction

The lower density than that of aluminum (around 30% less), makes the magnesium and its alloys an interesting material for the automotive and aeronautics industries, since this structural metal could allow the production of specific pieces and the construction of lighter vehicles. This strategy is related to the reduction of combusting consumptions of transport vehicles and the optimization of resources. Nonetheless, these alloys are highly susceptible to corrosion when exposed to aggressive environments, resulting on the loss of its mechanical characteristics. In the recent years, many magnesium alloys have been developed in order to increase both its mechanical and corrosion resistance [1–4]. This background leads to the research for alternative surface treatments for magnesium alloys excluding the use of dangerous compounds. The sol–gel route is a chemical way to produce harmless inorganic materials generally by using metallic alcoxydes, which may also contain organic functions (acrylic, vinyl, etc.) permitting the production of hybrid organic/inorganic materials and coatings with improved flexibility. In particular, the epoxy-based materials presents interesting characteristics like mechanical resistance and good chemical and thermic stability, superior to other types of hybrid materials [5–7]. A number of hybrid coatings have been produced for the corrosion protection of different metallic substrates such as steels [8], aluminum [9] or zinc alloys [10]. In the case of magnesium alloys, many authors have reported the use of this kind of coatings [11–16], showing a considerable degree of protection.

Commonly, the protective coatings applied on the automotive [17] and aeronautics [18] industries consists of a series of superposed layers of different chemical nature, which typically consists of a chemical/anodic conversion layer, an adhesion primer and an organic paint or finishing. Many surface treatments for magnesium alloys including a sol–gel conversion layer have been studied in combination with conversion layers [19,20], anodic coatings [21,22] or even multilayered sol–gel coatings [23–25], in order to provide a complex “architecture” to the protective anticorrosion system.

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The present work proposes an architectural approach to the production of an epoxy-based sol–gel coating, for the corrosion protection of a cast magnesium alloy (Mg–Nd–Gd–Zr–Zn). Usually, the metallic pieces obtained by low-pressure casting may contain a large amount of impurities at the surface, also presenting a very irregular and rough surface resulting from the contact with the mold. Hence, a chemical etching is generally applied for this kind of pieces in order to remove the contaminated and rough external layer before the application of protective coatings [26], though this surface pretreatment may expose the microstructure of the metallic substrate. On the other hand, the high reactivity of the magnesium substrate in aqueous media manifests itself when the sol contains a large portion of water, complicating the preparation of homogeneous coatings without pores and defects. Therefore, a bilayer epoxy-based sol–gel system is presented, where the first created sol–gel layer of sol would undergo the chemical reactions with the magnesium alloy, but thereby providing an inert surface for a second sol–gel layer which contribute to the thickening of the sol–gel coating. The morphological aspects of the sol–gel systems are analyzed by scanning electron microscopy, and their electrochemical properties are studied by OCP (open circuit potential) monitoring and electrochemical impedance spectroscopy in chloride media (0.05 M NaCl solution), in order to evaluate their corrosion resistance.

2. Experimental

2.1. Materials

2.1.1. Substrate preparation

The substrate consists of a cast Elektron21 (EV31A) magnesium alloy, provided by Fonderie Messier. After heat treatment (T6 code: heat solution and aging), large ingots of this alloy where cut and machined to obtain smaller coupons with dimensions of 40 × 20 × 6 mm. The composition of this magnesium alloy is presented on Table 1, furnished by the supplier.

After degreasing with acetone, the magnesium samples were polished with a SiC paper up to grade #1200, and subsequently rinsed with ethanol and dried with a stream of air. Then, the samples followed an acid etching with 20 g/L of HNO₃ for 2 min, followed by rinsing with ethanol and drying with a flux of air.

2.1.2. Sols and coatings preparation

The sols where produced by mixture of 3-glycidoxypropyltrimethoxysilane (GPTMS), aluminium-tri-sec-butoxide (ASB), deionized water and propanol in a molar ratio of 2:1:1:10. The mixture was kept under stirring for 2 h, followed by aging for 24 h at room temperature, before application on the magnesium samples. The viscosity of the sols was around 15 mPa s. The bilayer hybrid sol–gel coatings were obtained by the dip-coating technique, by immersing the magnesium samples into the sol, and withdrawing with a controlled speed of 50, 100, 200 or 400 mm/min, and subsequently realizing a heat treatment. The heat treatment includes two steps: drying at 50 °C for 2 h, and curing at 110 °C for 3 h. The protective coatings were obtained by applying one or two layers of hybrid sol–gel film, where for each layer produced a heat treatment was applied.

Table 1
Chemical composition of the cast magnesium alloy.

<table>
<thead>
<tr>
<th>Element</th>
<th>Nd</th>
<th>Gd</th>
<th>Zr</th>
<th>Zn</th>
<th>Other rare earths</th>
<th>Mg</th>
</tr>
</thead>
<tbody>
<tr>
<td>Wt.%</td>
<td>3.1</td>
<td>1.7</td>
<td>1.0</td>
<td>0.5</td>
<td>&lt;0.4</td>
<td>Balance</td>
</tr>
</tbody>
</table>

2.2. Characterization techniques

Viscosity of the sols was measured before production on the substrates with a Lamy RM-100 rheometer. The morphology of the magnesium substrate and coatings were analyzed by scanning electron microscopy (SEM) with a JEDL JSM-6510LV microscope, using an operating voltage of 20 kV. Electrochemical impedance spectroscopy (EIS) and open circuit potential ($E_{ocp}$) monitoring were performed in a 0.05 M NaCl solution at room temperature, using a NOVA frequency response analyzer and an AUTOLAB PGSTAT 30 potentiostat. The $E_{ocp}$ measurements were performed during the first hour of immersion of the samples in the corrosive solution. The measurements were performed using a three-electrode cell. The working electrode exposed area was 2 cm², with a reference and auxiliary electrodes consisting of a saturated calomel electrode (SCE) and a platinum foil electrode, respectively. The EIS spectra were drawn using a potentiostatic mode in the frequency range from 100 kHz to 10 mHz, with an applied voltage of 10 mV vs. $E_{ocp}$. The reproducibility of the tests was verified by analyzing three samples for each characterization technique.

3. Results and discussion

3.1. Magnesium substrate

The surface of the magnesium alloy samples after acid treatment is shown in Fig. 1a. The microstructure of the alloy shows the magnesium-rich grains, joined by two segregated regions. These regions correspond to neodymium-rich zones (grain boundaries) and to zirconium-rich zones (located inside the magnesium grains). On Fig. 1a, the irregularity of the surface of the alloy may be observed, where the zirconium-rich zones seem to be higher than the rest of the surface. Fig. 1b shows a cross-section SEM image of the substrate on back-scattered electrons (BSE) mode, where the presence of a white region (neodymium grain boundary), and a protuberance may be identified. The EDX analysis of the image reveals that the protuberance contains mainly zirconium (Fig. 1c). These zirconium-rich protuberances are supposedly created due to a lower dissolution rate of the zirconium than that of the magnesium grains and the neodymium-rich zones, during the acid etching.

3.2. Monolayer hybrid coating

3.2.1. Morphological characterization

The surface and the cross-section of the monolayer hybrid coating were observed by SEM (Fig. 2). It may be seen on the surface view of the sample (Fig. 2a) the irregular surface of the hybrid coating, which presents two kinds of defects: protuberances and pits. The cross-section view of the substrate on BSE mode (Fig. 2b) shows the average thickness of the hybrid coating, estimated to 5.2 ± 0.3 μm. As previously shown in Fig. 1b, the presence of protuberances may be observed, created by the zirconium-rich regions. At this location, the thickness of the film is reduced and disrupts the homogeneity of the coating. The second kind of defect, the pits, may be attributed to the reactivity of the alloy with the sol that produces a hydrogen evolution and therefore creating uncovered regions. 

3.2.2. Electrochemical measurements

The electrochemical behavior of the bare magnesium alloy, and covered monolayer hybrid coating (M) was analyzed by immersion in a corrosive solution containing 0.05 M of NaCl. The open circuit potential ($E_{ocp}$) was followed during the first hour of the immersion (Fig. 3).

From the beginning of the immersion, the $E_{ocp}$ value for the bare magnesium substrate rises with time, which is a phenomenon
associated to the development of a passivity layer as a result of the reaction between with the electrolyte. On the other hand, the potential of the substrate coated by the monolayer hybrid film stays constant from the beginning of the immersion at a higher potential than that of the bare substrate and remains stable for 1 h. At the end of the measurement, both magnesium bare, and coated magnesium by the monolayer hybrid film, showed an equivalent potential, of around −1.56 V. This behavior indicates that the monolayer hybrid film does not represent an efficient barrier between the substrate and the media.

After the $E_{ocp}$ monitoring, the electrochemical impedance spectroscopy (EIS) tests were performed (Fig. 4). This technique provides information about the interface of an electrochemical system, which can be the case of a corrosion process [27]. In specific, the impedance modulus at low frequency (Bode impedance modulus diagram) is ascribed to the global resistance of the electrochemical system [28]. Moreover, the phenomena shown on the Bode phase diagrams occur at characteristic frequencies that depend of the electrochemical system under study [29].

It may be seen on the Bode modulus diagram that the impedance modulus values of the monolayer hybrid system (M) drops considerably between 1 h and 24 h of immersion in the corrosive solution, and after 168 h this value is comparable to that of the bare magnesium substrate. This decrease is due to the progressive degradation of the coating induced by the aggressive electrolyte. For the bare magnesium substrate, it was observed a small increase in the impedance modulus values for 168 h of immersion, compared to 24 h of immersion, which can be attributed to the development and stabilization of a partially protective passivity layer at the surface of the metallic substrate [30,31].

For every immersion time (1, 24 and 168 h), the Bode phase angle diagram of the bare magnesium substrate shows the presence of two time constants, located at the middle frequency range (~20 Hz) and at the low frequency range (~100 mHz). These phenomena can be associated to the capacitive response of the passivity layer of the substrate, and to the charge and species exchanges between the substrate and the electrolyte [32], respectively.

On the other hand, the monolayer hybrid system shows the presence of a high frequency time constant (~100 kHz) at 1 h of immersion (Fig. 4a), which may be attributed to the barrier effect afforded by the epoxy-based coating [21,33]. After 24 h of immersion, the impedance modulus values for the monolayer hybrid system (M) continue to decrease, reaching a value comparable to that of the bare magnesium substrate after 168 h of immersion. This decrease is due to the progressive degradation of the coating induced by the aggressive electrolyte. For the bare magnesium substrate, it was observed a small increase in the impedance modulus values for 168 h of immersion, compared to 24 h of immersion, which can be attributed to the development and stabilization of a partially protective passivity layer at the surface of the metallic substrate [30,31].

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Immersion, the phase angle value for this time constant is considerably reduced and continues to decrease progressively with time. This decrease of the barrier properties of the film are related to the liquid intake of the film, which reduces its capacitance value [12,34], and progressively degrading the protective properties of the coating. At the same time (24h), it is possible to observe the apparition of a second time constant in the middle frequency range (∼100 Hz), the same region of that of the bare magnesium substrate, and which may be therefore associated to the formation of corrosion products at the metal/coating interface [35,36]. Moreover, after 168 h of immersion, both systems the bare substrate and coated by epoxy-based hybrid film, presents one comparable peak around 10 Hz, where in the case of the monolayer hybrid coating it may be attributed to the presence of a porous mixed layer of corrosion products and the sol–gel film. At this stage, the values of the hybrid coating (modulus and phase) are comparable to those of the bare magnesium substrate, meaning that the hybrid coating has lost its protective properties.
Table 2
Parameters used for the production of the bilayer sol–gel coatings A–D.

<table>
<thead>
<tr>
<th>Hybrid coating</th>
<th>Layer 1</th>
<th>Layer 2</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Withdrawal speed (mm/min)</td>
<td>Withdrawal speed (mm/min)</td>
</tr>
<tr>
<td>Monolayer</td>
<td>200</td>
<td>–</td>
</tr>
<tr>
<td>Bilayer</td>
<td>A 200 50</td>
<td>B 200 100</td>
</tr>
<tr>
<td></td>
<td>C 200 200</td>
<td>D 200 400</td>
</tr>
</tbody>
</table>

The interpretation of the results EIS obtained leads to consider that the monolayer hybrid coating offers an insufficient protection for the metallic substrate when exposed for long periods of time to the corrosive media. These results can be correlated to the SEM observations of the hybrid film that shows an irregular morphology, including macro-such as pits and protuberances, which represents sensible zones to the intrusion of corrosive species through the coating unto the magnesium substrate.

In order to provide a homogeneous and effective protection to the substrate, the architecture of the hybrid coating was modified by the addition of a second layer of the same epoxy composition.

3.3. Bilayer hybrid sol–gel coatings

3.3.1. Variation of the thickness of Layer 2

The "bilayer" architecture consists of a first layer, Layer 1 or "inerting layer", which would react with the magnesium substrate, partially leveling and "inerting" the surface. The second layer, Layer 2 or "thickening layer" would cover the defects presents on Layer 1 and increase the global thickness of the hybrid coating. In the first place, four bilayer systems were studied, consisting of a first epoxy-based layer (Layer 1) produced with a withdrawal speed of 200 mm/min. The second layer (Layer 2) was produced with withdrawal speeds of 50, 100, 200 and 400 mm/min, in order to obtain four bilayer systems of different global thickness, which are noted as A–D, respectively. After that, each layer followed a heat treatment as described on Table 2.

3.3.1.1. Morphological characterization. The SEM observation on mode BSE of the cross-section of the bilayer systems A–D is presented in Fig. 5. It is possible to observe that the global thickness of the coating increases with the withdrawal speed applied to the second layer. Besides, some irregularities of the magnesium substrate seem covered by the hybrid film, as it may be seen for the bilayer system D, where a protuberance appears under the surface of the hybrid coating.

Furthermore, the individual layers 1 and 2 are visible for most of the bilayer coatings, allowing the measurement of their average thickness. It is to notice that the thickness of the Layer 1 remains constant (5.2 ± 0.3 μm) for all the systems. Fig. 6 regroups the global thicknesses of these bilayer coatings and the individual thickness for each layer. Besides, it is important to underline that the

![Fig. 5. SEM images of the cross-section of the bilayer hybrid coatings A–D.](image)

![Fig. 6. Average individual layer thickness of the bilayer hybrid systems A–D.](image)
The thickness of the hybrid coating can be controlled directly on the metallic magnesium substrate, or over a previously sol–gel coated surface of the same nature.

The observation of the surface of the different hybrid bilayer coatings by SEM (Fig. 7) permits to notice the absence of defects and uncovered areas, previously seen on the monolayer hybrid coating. This means that the second layer of hybrid film has recovered this kind of defects, even for the lowest thickness of Layer 2 (bilayer system A, 2.3 ± 0.3 μm). Moreover, it may be seen that the irregularities formed by protuberances are less visible as the global thickness of the coating increases, leading to more homogeneous surfaces. This is especially observed in the case of the bilayer systems presenting a thickness equivalent or superior to ∼11 μm (coatings C and D), where the homogeneity of the hybrid film seem considerably improved, meaning these defects can be covered with a proper thickness of hybrid film.

3.3.1.2. Electrochemical measurements. The E_ocp records of the bare magnesium substrate and coated by the bilayer systems A–D during the immersion on the corrosive solution (0.05 M NaCl) are presented in Fig. 8. It is to notice that the potential of the systems A and B is follows a similar behavior as the bare magnesium substrate, which is also comparable to that of the monolayer hybrid coating previously presented on Fig. 3. In contrast, the potential of the bilayer systems C and D is located in a region of nobler potentials, a first indication of a superior corrosion resistance for these two bilayer protective systems.

The EIS analyze of the systems A–D after 1 h of immersion in a 0.05 M NaCl solution (Fig. 9a) shows high impedance modulus values for all the systems, compared to the magnesium bare substrate. As well as, a high frequency time constant (ascribed to the barrier effect of the sol–gel film), can be observed representing the effectiveness of the protective coating during for short periods of contact with the corrosive solution. The impedance modulus values increase with the global thickness of the hybrid film.

However, the absorption of liquid into the hybrid film and the attack of corrosive species leads to the reduction of the impedance modulus values of the system, as it may be seen after 24 h of immersion (Fig. 9b), and finally after a much longer time period of 168 h (Fig. 9c), where both the low frequency impedance modulus and the high frequency time constant obtained for the protective systems A and B are comparable with that of the bare magnesium substrate. Moreover, the apparition of an intermediate layer of corrosion products at the substrate/coating interface is characterized by a well-defined second time constant in the middle frequency range (about 1–100 Hz). Nevertheless, here again the systems C and D shows a high value of both impedance modulus values and phase angle, even after 168 h of immersion in the corrosive media. This effect is more remarkable in the case of the bilayer system D, indicating that the electrochemical characteristics rises with the augmentation of the hybrid film thickness. Besides, for the bilayer system D it is not possible to observe the presence of the phenomenon in the middle frequency, observed for all the other systems and associated to the film degradation and corrosion.
products at the substrate/coating interface, which indicate the superior barrier effect of this hybrid film system compared to the others.

Although the systems A–D have all a second hybrid layer (Layer 2) that successfully covers the defects observed in the Layer 1, the electrochemical measurements show that the bilayer systems A and B have a similar behavior to that of the monolayer hybrid coating (M), losing its protective characteristics when in contact with the corrosive electrolyte for extended time periods. However, the thickness increase of the Layer 2 to \( \sim 5 \mu m \) or higher, permits to obtain higher electrochemical values for the system, and so to increase the durability of the protective hybrid coating. Here, it may be considered that a global thickness of \( \sim 11 \mu m \) is a threshold value permitting to achieve an effective anticorrosion protection for this epoxy-based bilayer coating.

The last bilayer systems presented have all an equivalent “inertion layer” thickness of around 5 \( \mu m \), and as a consequence, the influence of coating with a Layer 1 of different thickness, lower or higher than 5 \( \mu m \), is an interesting aspect to evaluate the corrosion resistance of these bilayer architectures. The next section of this work proposes the creation of two different thicknesses of Layer 1 for a similar thickness of Layer 2, in order to obtain two different bilayer systems.

### 3.3.2. Variation of the thickness of Layer 1

For the study of the thickness “inertion layer” (Layer 1) influence, two other bilayer systems were prepared, with the parameters listed on Table 3. These bilayer coatings are called \( D' \) and \( A' \), since

**Table 3** Parameters used for the production of the bilayer sol–gel coatings \( D' \) and \( A' \).

<table>
<thead>
<tr>
<th>Hybrid coating</th>
<th>Layer 1</th>
<th>Layer 2</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Withdrawal speed (mm/min)</td>
<td>Withdrawal speed (mm/min)</td>
</tr>
<tr>
<td><strong>Bilayer</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>( D' )</td>
<td>400</td>
<td>200</td>
</tr>
<tr>
<td>( A' )</td>
<td>50</td>
<td>200</td>
</tr>
</tbody>
</table>
it is expected to possess an equivalent global thickness to that of the systems D and A.

3.3.2.1. Morphological characterization. Fig. 10 shows the SEM observation (BSE mode) of the cross-section of the bilayer systems D′ and A′, permitting to measure the global and individual thickness of the bilayer coatings. These values are plotted on Fig. 11. It may be seen that the global thickness of the systems D and D′ are identical (around 18 μm), and the thickness obtained for each individual layer corresponds to the withdrawal speed applied during the dip-coating, even if the withdrawal speeds of Layer 1 and Layer 2 of the systems D and D′ are inverse. In other words, the global thickness for either systems D and D′ is equivalent, even if the thicknesses of the “inertion layer” and the “thickening layer” are different.

3.3.2.2. Electrochemical characterization. The results of the E_{ocp} measurements for the bilayer system D′ during the first hour of immersion on the corrosive solution are presented in Fig. 13, and compared with those obtained for the bilayer system D. With an identical global thickness, these bilayer systems (D and D′) show a similar behavior of potential during the immersion, located in a nobler region than that of the bare magnesium alloy, and to the bilayer systems A and B previously presented. The high values of potential presented by the system D′ denotes an efficient barrier effect that temporary prevents the passage of the electrolyte unto the metallic substrate.

After the OCP measurements, the bilayer system D′ samples were analyzed by EIS in the corrosive solution, showing that this protective coating possess a high impedance modulus and phase angle values, in the first hours of immersion (Fig. 14a). This behavior can be associated to the high barrier effect of these hybrid films (bilayer system D and D′, which present the same global thickness layer, around 18um). Nonetheless, both the resistance and the phase angle of the bilayer system D′, which presents the higher Layer 1 thickness (13um), decreases dramatically after 24 h in contact with the aggressive solution (Fig. 14b). Furthermore, the impedance modulus values of this system are similar to those of the bare magnesium substrate after 168 h of immersion, representing the major degradation of the protective properties of this coating. It is important to underline the difference on behavior between these systems of identical global thickness: D and D′. The bilayer system D shows a high impedance modulus and phase angle values at the end of the EIS test (168 h of immersion), that may be ascribed to an efficient barrier effect. On the other hand, the bilayer system D′ presents not only a rapid diminution of the impedance modulus and phase angle values), from 24 h of immersion, presented a well-defined second time constant in the middle frequency, which evidences the formation of corrosion products, result of the interaction between the electrolyte and the magnesium substrate, as it was mentioned before.

This example shows that coating with a thicker “inertion layer” under these conditions does not necessarily leads to an increase of the corrosion resistance. The sol–gel coatings (>1 μm) are susceptible to cracking [37], and also diminishes the evaporation rate of solvents during drying [38]. In that case, the creation of a Layer 1
with $13 \pm 0.3 \mu m$ of thickness may represent an excessive amount of solvents that could not be completely evaporated applying the current heat treatment. Imprisoned inside the hybrid film, the solvents and water would disable the full reticulation and consolidation of the solid network of the sol–gel film and therefore permitting the passage of liquid and corrosive species unto the metallic substrate.

It is important to underline the fact that the “inertion layer” (Layer 1) of all the bilayer systems here presented undergoes a heat treatment twice: the first one is applied after coating with Layer 1 and the second is indirectly applied at the same time for Layer 2. This means that the solid network of Layer 1 would be better consolidated than that of Layer 2. Even though the “inertion layer” of the systems D and D’ followed an identical heat treatment, their thickness would seem to be a crucial factor on the corrosion protection of the magnesium substrate.

Fig. 13. Open circuit potential ($E_{ocp}$) registered for the bilayer systems: D and D’, during the first hour of immersion in the corrosive solution (0.05 M NaCl).

As for the “thickening layer” (Layer 2), the solvents and water are able to escape even after the drying stage of the coating, since this layer remain in direct contact with the environment. Hence, even if

Fig. 14. Bode diagrams of the EIS spectra obtained for the bare magnesium substrate, and covered by the bilayer systems D and D’, after 1 h (a), 24 h (b) and 168 h (c) of immersion in 0.05 M of NaCl.
the "thickening layer" presents an important thickness (∼13 μm), as it is the case of the bilayer system D, it can evaporate the solvents easily because there is no solid barrier between this layer and the environment. On the other hand, in the case where the thickest layer is the "inertion layer" (Layer 1), as for the bilayer system D′ (∼13 μm), the "thickening layer" (Layer 2) would act as a physical barrier that partially obstructs the evaporation of solvents and water during drying of the coating.

Despite these two bilayer coatings possess the same global thickness, they show a remarkable difference in anticorrosion performances, as it has been proved by the electrochemical tests. Here, the bilayer system D presents the best electrochemical values, and so the best corrosion performances. With an equivalent global thickness to system D′, the "inertion layer" of this bilayer coating is of about 5 μm thick, which would contain an inferior quantity of solvents easier to evaporate, permitting to achieve a better reticulation than an "inertion layer" of ∼13 μm.

In this context, the preparation of a bilayer coating with an "inertion layer" inferior to ∼5 μm, which is the case of the bilayer system...
A’, would help to support the previous observations. First, the $E_{\text{ocp}}$ record of this coating (Fig. 15) during the first hour of immersion in the corrosive solution shows no remarkable difference with the behavior shown by the bilayer system A, which possess an equivalent global thickness. Besides, both of the hybrid films present an $E_{\text{ocp}}$ potential equivalent to that of the bare magnesium substrate and to the monolayer hybrid coating (Fig. 3).

The EIS spectra of the bilayer system A’ at 1 h, 24 h and 168 h (Fig. 16), shows a similar behavior to that of the bilayer system A. And the impedance modulus values of these systems decreases at similar rates with the immersion time. Besides, the high frequency time constant observed in these coatings diminishes simultaneously with the immersion time, probably due to the formation of corrosion products after 24 h (depicted by a middle frequency time constant). For these two bilayer coatings of equivalent global thickness, A and A’, the change on thickness for the “inertion layer” do not modifies considerably the electrochemical properties of the system.

From another point of view, both systems D’ and A’ possess an identical Layer 2 (~5 μm), as well as the previously presented system C. Here, these three bilayer systems present an equivalent thickness of Layer 2, with an increasing thickness of Layer 1 in the order: A’, C and D’. Fig. 12 regroups the individual layer thickness for these systems. It is important to underline that the electrochemical characteristics of system A’ have been shown to behave in the same way of the monolayer hybrid coating, insufficient to ensure the protection of the metallic substrate. In contrast, when the thickness of Layer 1 is equivalent to ~5 μm (system C), the protective performances of the coating considerably increase. However, the creation of an “inertion layer” with a significant thickness (~13 μm) like in the case of the system D’, the protective properties of the coating are severely diminished. The thickness of Layer 1 seem to have a strong influence on the final properties of the bilayer coating, rising the durability of the system when it’s thickness is equivalent to 5 μm, as it is observed in the case of system C. In the case of an important thickness (13 μm), this may represent an excessive amount of solvents to evaporate so the full reticulation of the coating is not achieved, as it was observed in the case of the system D’.

The electrochemical results here presented suggest a strong relationship between the architecture of the bilayer systems and their anticorrosion performances. The first part of the study of bilayer systems: A–D, with a Layer 1 thickness of 5.2 ± 0.3 μm, have shown that it is necessary to increase the thickness of the Layer 2 equal or greater than ~5 μm in order to achieve satisfactory anticorrosion performances. Lower thicknesses for this second hybrid layer will lead to performances comparable to those of a monolayer film.

Finally, the second part of the study of bilayer systems, it was observed that increasing the thickness of the “inertion layer” will not necessarily improve the anticorrosion performances of the system, as it was noted for the bilayer coating D’, which presents a Layer 1 thickness equivalent to ~13 μm. On the other hand, coating with an “inertion layer” of inferior thickness (~2 μm) has no significant influence on the anticorrosion performances, when compared to a bilayer system with an equivalent global thickness as it was shown for the systems A and A’.

An important influence of the thicknesses of both the “inertion layer” and the “thickening layer” is observed, which may be attributed to parameters like the solvent accumulation and evaporation inside Layer 1, the reticulation and condensation degree of the sol–gel network, the heat treatment performed or even the reactivity of the magnesium substrate.

4. Conclusions

The present work reports the use of different architectural arrangements for a bilayer epoxy-based sol–gel coating for the corrosion protection of a magnesium alloy. The morphological analyze of the monolayer architecture evidences the presence of macro-defects which would potentially decrease the anticorrosion protection of this coating, as it is shown by the EIS analyze in a chloride solution. Therefore, a second or “thickening” layer of the epoxy-based coating was added in order to cover the defects of the first or “inertion” layer, and also to increase the global thickness of the coating.

First, it is shown that for an “inertion layer” of a thickness of 5 μm, the “thickening” layer shall present the same thickness (5 μm) in order to increase the anticorrosion performances of the system. Otherwise the bilayer system shows the same performances resembles to those of the monolayer architecture of the epoxy-based coating. The best anticorrosion performances were obtained for the bilayer system presenting the highest global thickness (18 μm), the system D.

Second, the thickness of the second layer was set to a constant value of ~5 μm as for the “inertion” layer it was increased to ~13 μm, resulting on lower anticorrosion performances compared to a coating with equivalent global thickness but inversed architecture. Here, the accumulation of solvents inside the “inertion” layer would lead to a lower reticulation degree, and so to the diminution of the protective properties of the bilayer system.

The study of the epoxy-based sol–gel film here presented shows that a single layer of this coating is not enough to ensure the protection of the magnesium alloy, and that it may be covered with a second layer of the same chemical nature. However, the architecture of this coating has an important role on the final anticorrosion performances of the system, just as much as the thickness of the protective system.

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