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Patterning the distribution of threatened crayfish and their exotic analogues using self-organizing maps

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SUMMARY

Ability to demonstrate statistical patterns of distribution by threatened species and by their potential competitors will determine success in forecasting locations at greatest risk, and ability to target management efforts. A self-organizing map algorithm (SOM) was used to derive probabilities of presence of native (Austropotamobius pallipes) and exotic (Orconectes limosus, Pacifastacus leniusculus and Procambarus clarkii) crayfish species with respect to physical and land-cover variables in a large stream system, using a simple presence-abscence dataset of species. Crayfish were sampled at 128 sites representing 86 rivers. The probability of occurrence of the native species increased at higher elevations above sea level and lower temperatures; populations appeared to be mostly confined to headwater streams where exotic competitors were unable to withstand the colder conditions. The distribution of exotic species was correlated with anthropogenic factors, such as the degree of urbanization and agricultural land area. Complementary modelling tools, such as GIS and SOMs, can help to maximize the information extracted from available data in the context of biological conservation.

Keywords: freshwater, land use, neural networks, occurrence, species distribution

INTRODUCTION

At the onset of most action plans directed towards the conservation of threatened species at regional and/or national scales, numerical patterning is needed to ‘map’ the current distribution of populations in the area under survey, and, whenever possible, estimate abundances and densities (see Guisan & Zimmerman 2000 for a review). Eventually, similar information is required for non-native ecological analogues, when competitive interactions are likely to adversely affect the native species (Morgan 1998; de la Hoz Franco & Budy 2005). A common way to examine the fit between species distributions and habitat is through ordination and correlation of habitat and biotic variables. However, for many non-mutually exclusive reasons (for example time- and cost-efforts, species seasonality, detection difficulties and non-standardized sampling), quantitative data such as population densities cannot be consistently obtained over a large number of sampling sites (Margules & Austin 1994; Marshall et al. 2006), thus preventing conservationists from optimizing large but heterogeneous datasets built on the basis of field and/or literature data. There is therefore a need to develop alternative analytical approaches which can maximize the information extracted from available data, such as ‘simple’ presence-absence data (Manel et al. 1999; Bessa-Gomes & Petrucci-Fonseca 2003; Cérégine et al. 2005).

Inspired by the structure and the mechanism of the human brain, artificial neural networks (ANNs) provide convenient tools to extract information from large ecological datasets (Lek & Guegan 2000). The self-organizing map (SOM; Kohonen 2001) is one of the most well-known unsupervised neural networks, performing a topology-preserving projection of the input data onto a regular two-dimensional space. In the output layer of the network, the neurons act as virtual samples and approximate the probability density function of the input data. Therefore, using a binary dataset of species occurrences, the SOM calculates quantitative continuous values which vary between 0 and 1, so that the occurrence probability of any species in a given area, in the form of the connection intensity, can be visualized onto a virtual map. Moreover, this technique is relevant to pattern detection in ecological communities in relation to environmental data because the gradient distribution of some biological variables (for example species) can be visualized in a SOM previously trained with environmental variables only (Park et al. 2003), thus allowing the fit between a set of species and their environment to be examined.

Amongst threatened aquatic animals, crayfish are the focus of many conservation studies in the northern hemisphere (Gil-Sánchez & Alba-Tercedor 2002; Renal et al. 2006; Trouillé et al. 2007). Many factors closely related to fishing activities and/or human destruction of their physical and hydraulic habitats have led to declines (Light et al. 1995; Gil-Sánchez & Alba-Tercedor 2006). The white-clawed crayfish (Austropotamobius pallipes) is a listed species in Annex II of the European Community Habitats Directive 92/43/EEC.

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classified as ‘vulnerable’ on the Red List of Threatened Animals of the International Union for Conservation of Nature. However, because habitat and/or species surveys are time- and money-consuming, environmental managers and policy makers need general trends that could be adopted to plan specific measures. We used a SOM algorithm to interpret the probabilities of presence of native (Astroptomatobius pallipes) and exotic (Oncorhynchus limosus, Pacifastacus leniusculus, Procambarus clarkii) crayfish species with respect to physical and land-cover variables in the Adour-Garonne stream system (south-western France, 116 000 km²), using a binary dataset of species occurrences and GIS-derived information on river topology and land cover. Given the need to forecast locations at greatest risk of invasions, our study illustrates a cost-effective technique to target monitoring efforts.

METHODS

Study area and data collection

The Adour-Garonne stream system (south-western France) has a 116 000 km² drainage basin, which has been intensively studied for various ecological aspects (Tockner et al. 2009). The biological data and some physical variables were extracted from the French National Agency for Water and Aquatic Systems (Omene) database (BDMAP). We selected 128 sampling sites belonging to 86 streams, and ranging from 2 to 1080 m altitude. These sites were retained for our analyses because they were sampled by electrofishing during low-flow periods during 2002–2007, and they represented mountain, plain and coastal streams well.

Two-pass removal sampling was used whenever possible, by wading in smaller rivers and by boat in the larger ones. Four crayfish species were found to occur in the Adour-Garonne basin, among which one (white-clawed crayfish Astroptomatobius pallipes [Lereboulet 1858]) is native and three are exotic, namely the American crayfish Oncorhynchus limosus (Rafinesque 1817), signal crayfish Pacifastacus leniusculus (Dana 1852) and red-swamp crayfish Procambarus clarkii (Girard 1852). The biological variables assigned to each site were occurrences of native and exotic species.

The physical variables were elevation above sea level (asl, m), slope (%), distance from the source (km), drainage basin area (km²) and maximum air temperature in June (°C, namely the mean of maximum temperatures recorded by the French Meteorological Services in early summer during the whole sampling period).

For each site, a geographic information system (GIS, Mapinfo Professional 7.8) was used to delineate a geographical buffer zone representing a 1000 m-radius centred on the site. This scale is well suited to assign a land-cover influence to each site (see also Compin & Cérégghino 2007) and falls within that of the ‘Reach Buffer’ sensu Allan (2004), namely a buffer of 100 m to several 100 m in width on each bank and some hundreds of metres to a kilometre in length. A given site is most influenced by the one-kilometre area upstream of the circular buffer, however crayfish move upstream and downstream, and long-term movements are greater downstream than in the upstream direction (Buric et al. 2009). Thus, the downstream area of the circular buffer was intended to integrate possible influences of the surrounding landscape. Sampling sites were then characterized using the five physical variables described above, and three land-cover variables intended to account for anthropogenic pressure: buffer zone forest cover (%) area occupied by forest and woodland with native or exotic coniferous and/or deciduous trees, scrub and herbaceous vegetation associations), urban development (area covered by industrial, commercial and transport units, and artificial and non-agricultural vegetated areas), and agricultural area (arable land, permanent crops and pasture). Digital landcover information was obtained from the CORINE land-cover database for Europe (CLC 2000, see European Environment Agency website at URL http://www.eea.europa.eu/; see also Cruckshank & Tolmison 1996). This database was generated from orthorectified satellite images and provides thematic GIS map layers including up to 44 land-cover classes with a mapping scale of 1:100 000. The eight variables were chosen because they characterize the location of sampling sites within the stream system and within the regional landscape mosaic, and were easy to describe using a GIS. The use of simple variables in a successful final model could thus reduce the effort and cost of data collection for water management applications.

Modelling procedure

Because ecological and environmental data often vary and vary in a nonlinear fashion, nonlinear modelling methods such as artificial neural networks (ANNs) should theoretically deal better with such data. Combining ordination, clustering, and gradient analysis functions, the SOM (see Kohonen 2001 for details) is relevant to the analysis of non-linear data and/or variables that have skewed distributions, without an a priori transformation (Park et al. 2003). Additionally, the SOM algorithm averages the input dataset using weight vectors and thus removes noise. These features were relevant in our study because we analysed a presence/absence dataset with many zeroes.

The SOM Toolbox (version 2) for Matlab developed by the Laboratory of Information and Computer Science at the Helsinki University of Technology (http://www.cis.hut.fi/projects/somtoolbox/) was used (see Vesanlo et al. 1999 for practical instructions). The structure of the SOM for our study consisted of two layers of neurons connected by weights (i.e. connection intensities): the input layer was constituted by 12 neurons (one per variable, but see below) connected to the 128 samples (sites), the output layer was constituted by 56 neurons (visualized as hexagonal cells) organized on an array with eight rows and seven columns. In the output layer, the neurons acted as virtual sites and approximated the probability density function of the input data. During the training, we used a mask function to
give a null weight to the four biological variables (crayfish occurrences), whereas environmental variables were given a weight of 1 so that the ordination process was based on the eight environmental variables only (Compin & Céréghino 2007). Setting mask value to zero for a given component removed the effect of that component on organization (Sirola et al. 2004). The occurrence probability of each crayfish species in a given area in the form of the connection intensity was visualized on the SOM map in grey scale, and therefore allowed us: (1) to analyse the effect of each environmental variable on the patterning input dataset (sites), and (2) to predict the occurrence probability of each species in areas (i.e. subsets of sites or clusters) where they were not consistently collected during the sampling.

The SOM algorithm is an unsupervised learning procedure which can be summarized as follows. The virtual sites were initialized with random samples drawn from the input data set. The virtual sites were updated in an iterative way. A sample unit was randomly chosen as an input unit. The Euclidean distance between this sample unit and every virtual site was computed. The virtual site closest to the input was selected and called 'best matching unit' (BMU). The BMU and its neighbours were moved a bit towards the input unit.

The training was broken down into two phases (Lek & Guégan 2000): (1) an ordering phase (the first 2000 steps): when this first phase takes place, the sites are highly modified in a wide neighbourhood of the BMU. (2) A tuning phase (75 000 steps): during this phase, only the virtual sites adjacent to the BMU are lightly modified.

The map size is important to detect the deviation of the data. Specifically, if the map is too large (i.e. when the number of map units is as large or larger than the number of samples), it is possible to 'overfit' the model (Park et al. 2003). Therefore, the network was trained with different map sizes (10–200 units), and the optimum map size was chosen based on local minimum values for quantization and topographic errors (see Céréghino & Park 2009). Quantization error (QE) is the average distance between each data vector and its BMU and, thus, measures map resolution (Kohonen 2001). Topographic error (TE) measures map quality (i.e. it assesses whether the map has been properly trained), representing the proportion of all data vectors for which 1st and 2nd BMUs are not adjacent, and is thus used for the measurement of topology preservation. The total of 56 output neurons retained for this study fitted the heuristic rule of Vesanto et al. (2000) well. Vesanto et al. (2000) reported that the optimal number of map units C is close to $C = \sqrt[5]{n}$, where $n$ is the number of samples; in the present case 128 sampling sites were classified on the basis of eight environmental variables. At the end of the learning process, each sampling site was set in the corresponding hexagon of the SOM. Neurons that were neighbours on the grid were expected to represent neighbouring clusters of sites; consequently, sites separated by a large distance from each other, according to environmental variables, were expected to be distant from each other in the output space.

A k-means algorithm was applied to cluster the trained map. The SOM units (hexagons) were divided into clusters according to the weight vectors of the neurons, and clusters were justified according to the lowest Davies Bouldin Index (i.e. for a solution with low variance within clusters and high variance between clusters). A GIS was used to visualize the modelled structures (clusters of sites) further in a more popular way.

**RESULTS**

After training the SOM, the k-means algorithm helped to derive four clusters, based on the minimum Davies Bouldin Index (DBI = 1.0465, 0.9684, 0.8486 and 1.0012 for a solution with 2, 3, 4 and 5 clusters, respectively). Thus, sampling sites were classified into four subsets according to eight environmental variables (Fig. 1). Clusters were plotted on a geographical map of the Adour-Garonne Basin in order to ease interpretations (Fig. 2).

Sites in clusters A and B corresponded to headwater streams located at higher altitudes (Fig. 1). Within this frame, cluster A was delineated by higher proportions of forested areas (Fig. 3), while cluster B was characterized by steeper slopes and lower summer temperatures. Sites in cluster C were located in urban landscapes and were characterized by higher air temperature, high distance from the source and the largest drainage basin area (Fig. 3). Finally, sites in cluster D were located at low elevation, and primarily corresponded to agricultural areas

![Figure 1 Distribution of the sampling sites on the self-organizing map (SOM). Codes correspond to sampling sites. Sites that are neighbours on the grid are expected to be similar in terms of environmental variables, and similarities decrease as sites are increasingly distant.](image)
The complex relationships between the spatial heterogeneity of physical conditions, and the local to regional distributions of target species have often been studied through correlative techniques (Jongman et al. 1995). Other authors have taken into account habitat variability, by considering the proportional use of particular habitats among the available ones (Hastie et al. 2000), but this approach is rather suited to the modelling of mesohabitat preferences on a local scale. However, the need for quantitative data, collected in a standardized manner, is a prerequisite for the use of correlative techniques and habitat modelling. The SOM algorithm (Kohonen 1982) is a heuristic model used to visualize and explore linear and non-linear relationships in high-dimensional datasets. SOMs were first used in the 1980s in speech recognition (Kohonen et al. 1984). Since Chon et al. (1996) first applied the SOM to pattern benthic communities in streams, SOMs have been implemented in various aspects of water research, such as classifying biological and environmental data (Gevrey et al. 2004; Tison et al. 2004) and patterning long-term data (Kangur et al. 2007). Although the SOM visualization is an indirect gradient analysis like a principal component analysis, SOMs can be used as an analysis tool to establish the relationships between sampling sites, and environmental and biological variables. The advantages of the SOM in comparison with conventional multivariate analyses have been established (Gevrey et al. 2003). In adding to the calculation of occurrence probabilities using binary data, it is important to highlight one of the most innovative applications of the SOM for conservation issues: the possibility of introducing a set of variables (for example biological variables) into a SOM that has been previously trained with other variables (for example environmental variables). This application, which enables researchers to tease out the relationships between two sets of variables, is convenient to examine the fit between species and their environment (as detailed in Céreghino & Park 2009). In this context, the SOM further maximizes the information extracted from large species matrices made of occurrence data, by transforming binary values into probabilities of presence, then allowing the comparison of environmental gradients and the likelihood that species will occur. Comparison among closely related species can also be made; any species association can be indicated by overlapping several maps. Thus, this
Figure 3 Gradient analysis of each variable on the trained SOM, with visualization in shading scale (dark = high values, light = low values). Each individual map is to be compared with, or superimposed onto, the map in Figure 1.

The approach can better analyse relationships between variables than general indirect gradient analysis.

The model probabilities of presence of native A. pallipes showed good agreement with current distributions at the watershed scale. In many European countries, the white-clawed crayfish is one of the most widespread decapod crustaceans (Holdich 2002), but both species distribution and population densities have drastically declined during the last decade (Gil-Sánchez & Alba-Tercedor 2006). At the catchment scale, populations are scarce and reduced to marginal areas of stream systems, which are often disconnected from the main stream (Gil-Sánchez & Alba-Tercedor 2002, Bramard et al. 2006). Such observations reveal that some river sections remain more suitable than others in terms of habitat conditions, and this pattern was clearly illustrated in our study by differences in probabilities of presence among neighbouring sites within the stream system.

However, as it is often reported, A. pallipes populations appeared to be mostly confined to headwater streams (i.e., colder waters), almost certainly because exotic competitors were unable to withstand the colder conditions that prevail in mountainous areas (Gil-Sánchez & Alba-Tercedor 2002; Legalle et al. 2008). Introduced crayfish usually grow faster, have a greater size and less restricted habitat requirements than native species (Changeux 2003; Dunn et al. 2009).

Such ecological advantages are detrimental to the partition of habitat and food resource, and native populations subjected to antagonistic interactions with such species may rapidly decline to extinction (Gil-Sánchez & Alba-Tercedor 2006). Moreover, foreign species may be predators on native species, and/or may be vectors of diseases (Moyle & Light 1996; Gozlan et al. 2006). This problem typically affects the white-clawed crayfish. The introduction of Orconectes limosus, Pacifastacus leniusculus and Procambarus clarkii (among others) was the main reason for the decline of A. pallipes in the downstream sections of European rivers, as it led to a competitive exclusion of native crayfish (Vorburger & Ribi 1999; Dunn et al. 2009), and brought the crayfish plague caused by the fungus Aphanomyces astaci (Kozubiková et al. 2008).

Although A. pallipes and P. leniusculus had quite distinct geographic distributions (Fig. 2b), they showed rather similar preferences for local environments. Gradient distributions for P. leniusculus (Fig. 4) could be perceived as a negative picture of the gradient depicting the distribution of A. pallipes. Our analyses suggest that A. pallipes and P. leniusculus have different preferences within a common range of headwater environments for certain variables such as slope and land cover. Conversely, such a pattern also suggests that competitive exclusion occurs within the stream system, and that subsequent competition with the exotic species P. leniusculus is a key factor explaining the current distribution of A. pallipes within the stream system. P. leniusculus is indeed recognized as the principal competitor of A. pallipes (Changeux 2003; Bramard et al. 2006). This highly invasive species commonly leads to the displacement of native A. pallipes. According to probabilities of occurrence, Procambarus clarkii and Orconectes limosus had distinct distributions that showed little spatial overlap with any other species. Procambarus clarkii is well adapted to life in agricultural areas;
translocations have been most successful in agricultural areas employing irrigation systems (Hobbs et al. 1989). In Spain, this species has severe impacts on rice agriculture (Cruz & Rebele 2007), while in France, it often occurs in marshy and rice areas (Bramard et al. 2006). Although P. clarkii is often described as a competitor of A. pallipes, our results show that its habitat preferences differ from those of A. pallipes, resulting in a spatial segregation of the species. In fact, P. clarkii seems to be unable to colonize mountainous headwater streams where A. pallipes has found refuge (Gil-Sánchez & Alba-Tercedor 2002). Orconectes limosus occurs in urbanized areas corresponding to lower elevation streams. In the other European countries, the American spiny-cheek crayfish (O. limosus) is also mainly found in lower reaches of watercourses (Petrucek et al. 2006) or in large lakes (Schulz et al. 2002) and does not penetrate far upstream. Its distribution in standing waters is largely the result of intentional human-mediated translocations (Petrucek et al. 2006) and reflects the intensity of human activities (Schulz et al. 2002).

Manel et al. (1999) demonstrate that the overall success of prediction of ANNs is superior to that of logistic regression and discriminant analyses when predicting the presence or absence of river birds according to the environmental variables. ANN predictions outperformed logistic regression, linear discriminant analysis and classifications trees approaches for predicting fish species presence/absence (Olden & Jackson 2001). This independence from assumptions makes ANNs a powerful option for exploring complex potential non-linear relationships such as the associations between animal species and their environment (Joy & Death 2004). ANNs also allowed a single model to predict the entire considered assemblage in one procedure (Joy & Death 2004). Studies involving predictive modeling of species occurrence increasingly combine the power of GIS with multivariate statistical tools to formalize the link between species and their environment and to enhance the potential to create accurate predictive models (Joy & Death 2004). In this study, the predictions from the ANN using land cover information (obtained from GIS) and simple environmental data showed that SOMs are a valuable technique to forecast crayfish distributions. This technique yields a clear bidimensional projection of a relatively large volume of site-specific data on species occurrences and then allows their interpretation in terms of occurrence probabilities of species in different geographic areas. Moreover, by overlapping various species maps (for example Fig. 4), any spatial overlap or segregation of the different species become clear. Most surveillance techniques for aquatic aliens use extensive numbers of site-specific data to allow predictions of the distribution of species in a given area, using a set of environmental variables (Ricciardi & Rasmussen 1998). The SOM visualization can be used as an analytical tool to bring out relationships between sample locations, biological variables and the occurrence of each species. Our study demonstrates the association of two modelling tools (GIS and neural networks) could improve ecological risk assessments; the techniques may have many potential uses, notably to identify areas in need for protection or areas suitable for reintroduction of endangered species such as the white-clawed A. pallipes.

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